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## Strong Convergence of Split-Step Forward Methods for Stochastic Differential Equations Driven by $S\alpha S$ processes

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**Abstract.** We consider stochastic differential equation driven by  $\alpha$ -stable processes. Three methods of drifting split-step Euler, diffused split-step Euler and three-stage Milstein for approximation of solution are used. The strong convergence of these three methods is proven and the upper bounds of their stabilities are obtained and depicted.

**AMS Subject Classification:** 60H10, 65C35, 60H35, 62L20.

**Keywords and Phrases:** Stochastic differential equation; Split step forward method,  $\alpha$ -stable process; Strong convergence; Absolute-value stability.

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## 1 Introduction

We consider one-dimensional time-independent Stable Lévy SDE's of the following form

$$\begin{cases} dX(t) = \mu(X(t)) dt + \sigma(X(t)) dS_\alpha(t), & t \in [t_0, T] \\ X(t_0) = X_0. \end{cases} \quad (1)$$

where  $X(t)$  is a real-valued stochastic process and  $\mu, \sigma$  are real well-defined functions.  $\{S_\alpha(t), t \in [t_0, T]\}$  is  $S_\alpha S$  process with  $\alpha \in (1, 2]$  (for more details see [1, Page 30]). In this article, numerical methods on a given time interval  $[t_0, T]$  are fixed by schemes based on equidistance time discretization points  $t_n = t_0 + nh$ ,  $n = 0, 1, \dots, N$  with step size  $h = \frac{T-t_0}{N}$ ,  $N = 1, 2, \dots$ . We focus our attention that convergence in the strong sense. An approximation  $X_n$  convergence strongly to the exact solution  $X(t_n)$  with order  $p > 0$  if there exist constants  $h_0, c \in (0, +\infty)$ , such that for all  $h \in (0, h_0)$

$$\mathbb{E}|X(t_n) - X_n| \leq ch^p.$$

For SDE (1), the well-known Euler–Maruyama (EM) method is given by [1, Page 157]

$$X_{n+1} = X_n + \mu(X_n)h + \sigma(X_n)\Delta S_\alpha(t_n)$$

where  $\Delta S_\alpha(t_n) = S_\alpha(t_{n+1}) - S_\alpha(t_n)$ , two split-step forward methods takes attention of consideration.

The first one is drifting split-step Euler (DRSSE) method [5]

$$\begin{cases} \hat{X}_n = X_n + h\mu(X_n) \\ X_{n+1} = \hat{X}_n + \Delta S_\alpha(t_n)\sigma(\hat{X}_n) \end{cases}$$

The second type is called diffused split-step Euler (DISSE) method [5]:

$$\begin{cases} \hat{X}_n = X_n + \sigma(X_n)\Delta S_\alpha(t_n) \\ X_{n+1} = \hat{X}_n + h\mu(X_n) \end{cases}$$

Following classical three-stage Milstein (TSM) method we define the following TSM method.

$$\begin{cases} \widehat{X}_{n1} = X_n - \frac{1}{2}h^{\frac{2}{\alpha}} \sigma(X_n) \sigma'(X_n) \\ \widehat{X}_{n2} = \widehat{X}_{n1} + h \mu(\widehat{X}_{n1}) \\ X_{n+1} = \widehat{X}_{n2} + \Delta S_\alpha \sigma(\widehat{X}_{n2}) + \frac{1}{2}h^{\frac{1}{\alpha}} \sigma(\widehat{X}_{n2}) \sigma'(\widehat{X}_{n2}) \Delta S_\alpha \end{cases}$$

The following assumptions are required when considering the convergence properties of splitting schemes for SDE

**Assumption 1.1** ([10, 5]). *The functions  $\mu(\cdot)$ ,  $\sigma(\cdot)$  and  $\sigma(\cdot)\sigma'(\cdot)$  satisfy Lipschitz condition, i.e, there exist positive real  $k_1$  such that*

$$|\mu(x_1) - \mu(x_2)| \vee |\sigma(x_1) - \sigma(x_2)| \vee |\sigma(x_1)\sigma'(x_1) - \sigma(x_2)\sigma'(x_2)| \leq k_1|x_1 - x_2|$$

**Assumption 1.2** ([10, 5]). *The functions  $\mu(\cdot)$ ,  $\sigma(\cdot)$  and  $\sigma(\cdot)\sigma'(\cdot)$  satisfy  $\beta$ -growth condition for some  $\beta \in (1, \alpha)$ , i.e, for some constant  $k_2 \in \mathbb{R}^+$*

$$|\mu(x)|^\beta \vee |\sigma(x)|^\beta \vee |\sigma(x)\sigma'(x)|^\beta \leq k_2(1 + |x|^\beta)$$

In the Assumption 1.1 and Assumption 1.2,  $a \vee b$  means  $\max\{a, b\}$ .

**Lemma 1.3.** *If  $\mu$  and  $\sigma$  satisfy in Assumption 1.1 and if  $E|X_0| < \infty$  then  $E(\bar{X}_k) < \infty$  for  $k = 0, 1, \dots, N$  where*

$$\begin{aligned} \bar{X}_k &= \bar{X}_{t_{k-1}, X_{k-1}}(t_k) \\ &= \bar{X}_{k-1} + \mu(\bar{X}_{t_{k-1}})h + \sigma(\bar{X}_{t_{k-1}})\Delta S_\alpha(t_{k-1}), \quad k = 1, \dots, N \\ \bar{X}_0 &= X_0 = X(t_0) \end{aligned}$$

$$\bar{X}_{t,x}(t+h) = x + \mu(X(t))h + \sigma(X(t))\Delta S_\alpha(t)$$

**Proof.** First note that

$$\begin{aligned} \mathbb{E}(X_{t,x}(t+h) - \bar{X}_{t,x}(t+h)) &= \mathbb{E} \left[ \int_t^{t+h} [\mu(X(s)) - \mu(X(t))] ds \right. \\ &\quad \left. + \int_t^{t+h} [\sigma(X(s)) - \sigma(X(t))] dS_\alpha(s) \right] \end{aligned}$$

Therefore

$$\begin{aligned}
|\mathbb{E}(X_{t,x}(t+h) - \bar{X}_{t,x}(t+h))| &\leq \mathbb{E} \left[ \int_t^{t+h} [|\mu(X(s)) - \mu(X(t))| \right. \\
&\quad \left. + |\sigma(X(s)) - \sigma(X(t))|] ds \right] \\
&\leq k \int_t^{t+h} [1 + |t-s|] ds \\
&\leq k(1+h)h
\end{aligned}$$

Now we have

$$\begin{aligned}
\mathbb{E} |\bar{X}_{k+1}| &= \mathbb{E} |\bar{X}_{t_k, \bar{X}_k}(t_{k+1})| \\
&= \mathbb{E} |\bar{X}_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_k + \bar{X}_k - X_{t_k, \bar{X}_k}(t_{k+1}) + X_{t_k, \bar{X}_k}(t_{k+1})| \\
&= \mathbb{E} |\bar{X}_k + (X_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_k) \\
&\quad + (\bar{X}_{t_k, \bar{X}_k}(t_{k+1}) - X_{t_k, \bar{X}_k}(t_{k+1}))| \\
&\leq \mathbb{E} |\bar{X}_k| + \mathbb{E} |X_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_k| \\
&\quad + \mathbb{E} |\bar{X}_{t_k, \bar{X}_k}(t_{k+1}) - X_{t_k, \bar{X}_k}(t_{k+1})|
\end{aligned}$$

So if  $\mathbb{E} |\bar{X}_k| < \infty$  then so is  $\mathbb{E} |\bar{X}_{k+1}|$ . In other words if  $\mathbb{E} |X_0| < \infty$  then  $\mathbb{E} (|\bar{X}_k|) < \infty$  for  $k = 1, 2, \dots, N$ .

The finiteness of the second part of inequality is verified as follows:

$$\begin{aligned}
\mathbb{E} |X_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_k| &= \mathbb{E} \left| \bar{X}_k + \int_{t_k}^{t_{k+1}} \mu(X(s)) ds \right. \\
&\quad \left. + \int_{t_k}^{t_{k+1}} \sigma(X(s)) dS_\alpha(s) - \bar{X}_k \right| \\
&= \mathbb{E} \left| \int_{t_k}^{t_{k+1}} \mu(X(s)) ds \right. \\
&\quad \left. + \int_{t_k}^{t_{k+1}} \sigma(X(s)) dS_\alpha(s) \right| \leq kh
\end{aligned}$$

□

**Lemma 1.4.** *If conditions of Assumption 1.3 satisfy, then*

$$\mathbb{E} |\bar{X}_k| \leq k(1 + \mathbb{E} |\bar{X}_0|)$$

**Proof.** By using the conditional version of Assumption 1.3, we have

$$\mathbb{E} \left| X_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_{t_k, \bar{X}_k}(t_{k+1}) \right| \leq k(1 + \mathbb{E} |\bar{X}_k|)h$$

consider again the inequality , we obtain

$$\mathbb{E} \left| X_{t_k, \bar{X}_k}(t_{k+1}) - \bar{X}_k \right| \leq k(1 + \mathbb{E} |\bar{X}_k|)h$$

or equivalently

$$\mathbb{E} |\bar{X}_{k+1}| \leq E |\bar{X}_k| + k(1 + \mathbb{E} |\bar{X}_k|)$$

Now using the well known resulting inequality given in Assumption 1.5 we obtain the result.  $\square$

**Lemma 1.5** ([2, Page 15]). *Suppose that for arbitrary  $N \in \mathbb{N}$  and  $k = 0, 1, \dots, N$  we have*

$$u_{k+1} \leq (1 + Ah)u_k + Bh^p \quad (2)$$

where  $h = \frac{T}{N}$ ,  $A, B \geq 0$ ,  $p \geq 1$ ,  $u_k \geq 0$ ,  $k = 0, 1, \dots, N$  then

$$u_k \leq e^{AT}u_0 + \frac{B}{A}(e^{AT} - 1)h^{p-1}. \quad (3)$$

## 2 Strong Convergence of DRSSE and DISSE

We now obtain the strong convergence of split step Euler method, under Assumption 1.1

**Theorem 2.1.** *Let  $X_k$  be the numerical approximation  $X(t_k)$  after  $k$  steps with step size  $h = \frac{T}{N}$ ,  $N = 1, 2, \dots$ .  $E|X_k| < \infty$ . Apply one of DRESE or DFSSE methods to the given SDE, under Assumption 1.1, then for all  $k = 0, 1, \dots, N$  we have*

$$\mathbb{E} \left( |X_k - X(t_k)| \middle| X(t_0) = X_0 \right) = O(h^{\frac{1}{2}})$$

**Proof.** We denote Euler-Maruyama approximation step by

$$E^{\text{EM}} = X_k + \mu(X_k)h + \sigma(X_k)\Delta S_\alpha(t_k), \quad k = 0, 1, \dots, N-1$$

then there exists constants  $k_1, k > 0$  such that

$$\begin{aligned} & \mathbb{E} \left( |X(t_{k+1}) - X_{k+1}| \mid X_k = X(t_k) \right) \\ & \leq \mathbb{E} \left( |X(t_{k+1}) - E_{k+1}^{\text{EM}}| \mid X_k = X(t_k) \right) \\ & + \mathbb{E} \left( |E_{k+1}^{\text{EM}} - X(t_{k+1})| \mid X_k = X(t_k) \right) \\ & \leq k(1 + \mathbb{E}|X_k|) + \mathbb{E} \left( |E_{k+1}^{\text{EM}} - X(t_{k+1})| \mid X_k = X(t_k) \right) \end{aligned}$$

Now

$$\begin{aligned} & \mathbb{E} \left( |E_{k+1}^{\text{EM}} - X(t_{k+1})| \mid X_k = X(t_k) \right) \\ & = \begin{cases} \text{for DRSSE method} \\ \mathbb{E} \left( |\sigma(X_{t_k}) - \sigma(X_k + h\mu(X_k))| |\Delta S_\alpha(t_k)| \mid X_k = X_{t_k} \right) \\ \text{for DFSSE method} \\ \mathbb{E} \left( |\sigma(X_{t_k}) - \sigma(X_k + h\mu(X_k))| |\Delta S_\alpha(t_k)| \mid X_k = X_{t_k} \right) \end{cases} \\ & \leq k_1(1 + \mathbb{E}|X_k|)h^{\frac{1}{2}} \end{aligned}$$

Therefore the inequality is less than or equal to  $k(1 + E|X_0|)h^{\frac{1}{2}}$ .  $\square$

**Lemma 2.2.** *Suppose the one-step approximation  $\overline{X}_{t,x}(t+h)$  has order of accuracy  $p_1$  for the mathematical expectation of the deviation and order of accuracy  $p_2$  for the  $\beta$ -growth deviation ( $1 \leq \beta < \alpha < 2$ ) more precicely, for arbitrary  $t_0 \leq t \leq t_0 + T - h$ ,  $x \in \mathbb{R}$  the following inequality hold:*

$$|\mathbb{E}(X_{t,x}(t+h) - \overline{X}_{t,x}(t+h))| \leq k(1 + |x|^\beta)^{\frac{1}{\beta}} h^{\frac{1}{p_1}} \quad (4)$$

$$[\mathbb{E}|X_{t,x}(t+h) - \overline{X}_{t,x}(t+h)|^\beta]^{\frac{1}{\beta}} \leq k(1 + |x|^\beta)^{\frac{1}{\beta}} h^{\frac{1}{p_2}} \quad (5)$$

**Proof.** By using Minkowski's inequality, we modified [2, Theorem 1.1] for  $\alpha$ -stable motion with  $\beta \in [1, \alpha]$  ( $1 < \alpha \leq 2$ ).  $\square$

**Lemma 2.3.** *Let for all natural number  $N$  and for all  $k = 0, 1, \dots, N$  we have  $\mathbb{E}(|X_k|^\beta) < \infty$ , where  $\beta$  is defined in Assumption 2.2. Then the following inequality hold:*

$$\mathbb{E}(|X_k|^\beta) \leq k \left(1 + \mathbb{E}|X_0|^\beta\right)$$

**Proof.** Suppose that  $\mathbb{E}|x_k|^\beta < \infty$ . Then using conditional version of (5) we obtain

$$\mathbb{E}|X_{t_k, x_k}(t_{k+1}) - \bar{X}_{t, x_k}(t_{k+1})| \leq k^\beta \left(1 + \mathbb{E}|x_k|^\beta\right)^\beta h^{p_2} \quad (6)$$

It is well-known that is a random variable  $X$  has bounded  $\beta$ -th moment, then the solution  $X_{t,x}(t+\theta)$  also has bounded  $\beta$ -th moment. Therefore  $\mathbb{E}|X_{t, x_k}(t_{k+1})|^\beta < \infty$  which implies  $\mathbb{E}|X_{k+1}|^\beta < \infty$ . Since  $\mathbb{E}|X_k|^\beta < \infty$  we have proved the existence of all  $\mathbb{E}|X_k|^\beta < \infty$ ,  $k = 0, \dots, N$ . Consider the inequality

$$(\mathbb{E}|X_{k+1}|^\beta)^{\frac{1}{\beta}} \leq (\mathbb{E}|X_k|^\beta)^{\frac{1}{\beta}} + (\mathbb{E}|X_{t_k, \bar{x}_k}(t_{k+1}) - X_k|)^\beta)^{\frac{1}{\beta}} \quad (7)$$

$$+ (\mathbb{E}|X_{t_k, \bar{x}_k}(t_{k+1}) - \bar{X}_{t_k, \bar{x}_k}(t_{k+1})|)^\beta)^{\frac{1}{\beta}} \quad (8)$$

we have

$$(\mathbb{E}|X_{t_k, \bar{x}_k}(t_{k+1}) - X_k|^\beta) \leq kh(1 + \mathbb{E}|X_k|^\beta) \quad (9)$$

It is not difficult to prove the inequality

$$\mathbb{E}|\mathbb{E}(X_{t_k, \bar{X}_k} - \bar{X}_k | X(t_k))|^\beta \leq kh^\beta(1 + \mathbb{E}|X_k|^\beta) \quad (10)$$

Applying the inequality (6), (8) and (9) to inequality (10) and recalling that  $p_1 \geq 1$ ,  $p_2 \geq \frac{1}{2}$ , we arrive at the inequality (for  $h \leq 1$ )

$$\mathbb{E}|X_{k+1}|^\beta \leq \mathbb{E}|X_k|^\beta + kh(1 + \mathbb{E}|X_k|^\beta) = kh + (1 + kh)\mathbb{E}|X_k|^\beta \quad (11)$$

Again using Assumption 1.5 we get to result.  $\square$

**Theorem 2.4.** *Let  $X_k$  be the numerical approximation to  $X(t_k)$  at time  $T$  after  $k$  steps with step size  $h = \frac{T}{N}$ ,  $N = 1, 2, \dots$ ,  $\mathbb{E}|X_k|^\beta < \infty$ , where  $1 \leq \beta < \alpha < 2$ . Apply one of split-step Euler methods to the SDE (1) under Assumption 1.2, then for all  $k = 0, 1, \dots, N$  we have*

$$\left[\mathbb{E}|X_k - X(t_k)|^\beta \mid X_0 = X(t_0)\right]^{\frac{1}{\beta}} = O(h^{\frac{1}{\beta}})$$

**Proof.** Let  $X_{k+1}^E$  stand for the local Euler approximation

$$X_{k+1}^E = X_k + h\mu(X_k) + \sigma(X_k)\Delta S_{\alpha k}, \quad k = 0, 1, \dots, N-1$$

then  $A_1 = \mathbb{E}^{\frac{1}{\beta}} \left( |X(t_{k+1}) - X_{k+1}^E|^\beta \mid X_0 = X(t_0) \right)$ . By using Minkowski's inequality, we have

$$\begin{aligned} A_1 &\leq \mathbb{E}^{\frac{1}{\beta}} \left( |X_{t_{k+1}} - X_{k+1}|^\beta \mid X_k = X(t_k) \right) \\ &\quad + \mathbb{E}^{\frac{1}{\beta}} \left( |X_{k+1}^E - X(t_{k+1})|^\beta \mid X_k = X(t_k) \right) \end{aligned}$$

But Lemma attain that

$$\begin{aligned} \mathbb{E}^{\frac{1}{\beta}} \left( |X(t_{k+1}) - X_{k+1}^E|^\beta \mid X_k = X(t_k) \right) &\leq k \left[ 1 + \mathbb{E} |X_k|^\beta \right] \\ &\leq k \left[ 1 + \mathbb{E} |X_k| \right]^{\frac{1}{\beta}} \end{aligned}$$

and

$$\begin{aligned} &\mathbb{E}^{\frac{1}{\beta}} \left[ |X(t_{k+1}) - X_{k+1}^E|^\beta \mid X_k = X(t_k) \right] \\ &= \begin{cases} \text{for DRSSE method} \\ \mathbb{E}^{\frac{1}{\beta}} \left[ \left| (\sigma(X_k) - \sigma(X_k^E))^\beta \Delta S_{\alpha k} \right|^\beta \mid X_k = X(t_k) \right] \\ \text{for DFSSE method} \\ \mathbb{E}^{\frac{1}{\beta}} \left[ \left| (\mu(X_k) - \mu(X_k^E))^\beta \Delta S_{\alpha k} \right|^\beta \mid X_k = X(t_k) \right] \end{cases} \end{aligned}$$

then

$$\mathbb{E}^{\frac{1}{\beta}} \left[ |X_{k_1}^E - X_{k+1}|^\beta \mid X_k = X(t_k) \right] \leq k_1 \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h^{\frac{3}{\beta}}$$

therefore

$$A \leq k \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h + k_1 \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h^{\frac{3}{\beta}}$$

but  $\frac{3}{2} \leq \frac{3}{\beta} < 3$  and therefore

$$\begin{aligned} \frac{k \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h + k_1 \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h^{\frac{3}{\beta}}}{h^{\frac{1}{\beta}}} &= k \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h^{1-\frac{1}{\beta}} \\ &\quad + k_1 \left[ 1 + \mathbb{E} |X_k|^\beta \right]^{\frac{1}{\beta}} h^{\frac{2}{\beta}} \end{aligned}$$

which tends to zero as  $h \rightarrow 0$ . The proof is complete  $\square$

**Theorem 2.5.** *Let  $X_k$  be the numerical approximation to  $X(t_k)$  at time  $t_k$  after  $k$  steps with step size  $h = \frac{T}{N}$ ,  $N = 1, 2, \dots$ . Apply the three-stage Milstein method to the SDE (1) under Assumption 1.1, and Assumption 1.2, then for all  $k = 0, 1, \dots, N$  we have*

$$\left( \mathbb{E} \left[ |X_k - X(t_k)|^\beta \middle| X_0 = X(t_0) \right] \right)^{\frac{1}{\beta}} = O(h),$$

where  $1 \leq \beta < \alpha < 2$ .

**Proof.** Denote the local Milstein approximation step

$$X_{n+1}^M = \widehat{X}_{n2} + \Delta S_\alpha \sigma(\widehat{X}_{n2}) + \frac{1}{2} \sigma(\widehat{X}_{n2}) \sigma'(\widehat{X}_{n2}) (\Delta S_\alpha)^2$$

then there exist some constant  $k > 0$  such that

$$\begin{aligned} H_1 &= \left| \mathbb{E} \left[ X(t_{n+1}) - X(t_n) \middle| X_n = X(t_n) \right] \right| \\ &= \left| \mathbb{E} \left[ X(t_{n+1}) - X_{n+1}^M \middle| X_n = X(t_n) \right] \right| \\ &\quad + \left| \mathbb{E} \left[ X_{n+1}^M - X_{n+1} \middle| X_n = X(t_n) \right] \right| \\ &\leq k (1 + \mathbb{E} |X_n|) h + H_2 \end{aligned}$$

with

$$\begin{aligned} H_2 &= \left| \mathbb{E} \left[ X_{n+1}^M - X_{n+1} \middle| X_n = X(t_n) \right] \right| \\ &\leq \begin{cases} \left| \mathbb{E} \left[ \Delta S_\alpha (\sigma(X_n) - \sigma(\overline{X}_{n2})) \middle| X_n = X(t_n) \right] \right| \\ \quad + \left| \mathbb{E} \left[ \frac{1}{2} (\Delta S_\alpha)^2 \sigma(X_n) \sigma'(X_n) - \sigma(\overline{X}_{n2}) \sigma'(\overline{X}_{n2}) \middle| X_n = X(t_n) \right] \right| \\ \quad + \left| \mathbb{E} \left[ h (\mu(X_n) - \mu(\overline{X}_{n1})) \middle| X_n = X(t_n) \right] \right|, \\ \text{if TSM method is used.} \end{cases} \end{aligned}$$

$$\begin{aligned} &\leq k_1 h \left( \left| \mathbb{E} \left[ X_n - \overline{X}_{n1} \middle| X_n = X(t_n) \right] \right| + \left| \mathbb{E} \left[ X_n - \overline{X}_{n2} \middle| X_n = X(t_n) \right] \right| \right) \\ &\leq k (1 + \mathbb{E} |X_n|) h \end{aligned}$$

similary we check estimate for local  $\beta$ -th mean of tree-stage Milstain and obtain for  $n = 0, 1, \dots, N - 1$  by standard arguments

$$\begin{aligned} H_3 &= \left( \mathbb{E} \left[ |X(t_{n+1}) - X_{n+1}|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ &\leq \left( \mathbb{E} \left[ |X(t_{n+1}) - X_{n+1}^M|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ &\quad + \left( \mathbb{E} \left[ |X_{n+1}^M - X_{n+1}|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ &\leq k \left( 1 + \mathbb{E} |X_n| \right)^{\frac{1}{\beta}} h^{\frac{3}{\beta}} + H_4 \end{aligned}$$

with

$$\begin{aligned} H_4 &= \left( \mathbb{E} \left[ |X_{n+1}^M - X_{n+1}|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ &\leq \begin{cases} \left( \mathbb{E} \left[ |\Delta S_\alpha (\sigma(X_n) - \sigma(\bar{X}_{n2}))|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ \quad + \left( \mathbb{E} \left[ \left| \frac{1}{2} \Delta S_\alpha (\sigma(X_n) \sigma'(X_n) - \sigma(X_{n2}) \sigma'(X_{n2})) \right| \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ \quad + \left( \mathbb{E} \left[ |h(\mu(X_n) - \mu(X_{n1}))|^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}}, \end{cases} \\ &\quad \text{if TSM method is used.} \\ &\leq k_1 h^{\frac{3}{\beta}} \left( \mathbb{E} \left[ (X_n - \bar{X}_{n1})^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \\ &\quad + \left( \mathbb{E} \left[ (X_n - \bar{X}_{n2})^\beta \mid X_n = X(t_n) \right] \right)^{\frac{1}{\beta}} \leq k \left( 1 + \mathbb{E} |X_n|^\beta \right) h^{\frac{3}{\beta}} \end{aligned}$$

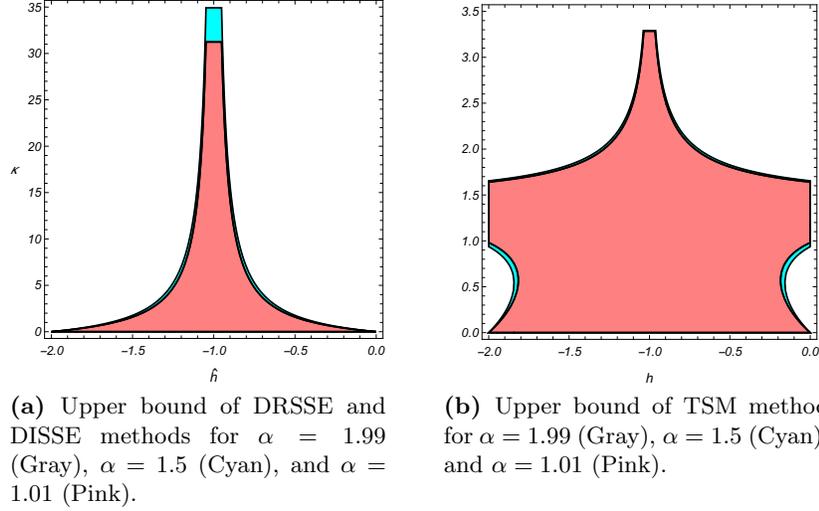
□

The last inequality is obtained under Assumption 1.2 and Assumption 2.3 the exponent  $p_2 = \frac{3}{\beta}$  together with  $p_1 = \beta$  and apply it to finally prove the strong order  $\gamma = 1$  of the three-stage Milstain methods as was claimed in theorem.

### 3 Stability properties

The stability of the methods are considered in this subsection we apply one-step scheme to the scalar linear test equation

$$dX(t) = \lambda X(t) dt + \mu X(t) dS_\alpha(t), \quad X(t_0) = X_0 \quad (12)$$



**Figure 1:** Stability bounds for  $\alpha = 1.99$ ,  $\alpha = 1.5$ , and  $\alpha = 1.01$ .

which is represented by

$$X_{n+1} = R(\hat{h}, \kappa, h, S)X_n$$

where  $S = S_\alpha(t_n)$  is stable random variable  $S \sim S_\alpha S$  with dispersion  $h$ ,  $\hat{h} = \lambda h$ , and  $\kappa = h^{\frac{1}{\alpha}} \mu$ . However, motivated by [10, 8, 5], we can extend the definition of stability and introduce absolute-value (AV) stability for  $\alpha$ -stable motion.

**Definition 3.1.** The numerical method is to be AV-stable for  $\hat{h}$ ,  $\kappa$  and  $h$  if

$$\overline{R}(\hat{h}, \kappa, h) = \mathbb{E} \left| R(\hat{h}, \kappa, h, S) \right| < 1$$

$\overline{R}(\hat{h}, \kappa, h)$  is called AV-stability function of the numerical method.

Applying one of DRSSE or DISSE to (12) we obtain

$$\begin{aligned} X_{n+1} &= (1 + \hat{h})(1 + \kappa S)X_n \\ &= R_1(\hat{h}, \kappa, h, S)X_n \end{aligned}$$

Then bound of AV-stability function of these methods is given by

$$\begin{aligned}\bar{R}_1 &= \mathbb{E}|R_1| = |1 + \hat{h}| \mathbb{E}(|1 + \kappa S|) \\ &\leq |1 + \hat{h}| (1 + |\kappa| \mathbb{E}|S|) \\ &= |1 + \hat{h}| \left(1 + \frac{2}{\pi} \kappa \Gamma\left(\frac{2}{\alpha}\right)\right)\end{aligned}$$

Now applying TSM method to (12) we obtain

$$\begin{aligned}X_{n+1} &= (1 + \hat{h}) \left(1 - \frac{1}{2}\kappa^2\right) \left(1 + \kappa S + \frac{1}{2}\kappa^2 S\right) X_n \\ &= R_2(\hat{h}, \kappa, h, S) X_n\end{aligned}$$

$$\begin{aligned}\bar{R}_2 &= \mathbb{E}|R_2| = |1 + \hat{h}| \left|1 - \frac{1}{2}\kappa^2\right| |1 + \kappa S + \frac{1}{2}\kappa^2 S| \\ &\leq |1 + \hat{h}| \left|1 - \frac{1}{2}\kappa^2\right| \left(1 + \left(\kappa + \frac{1}{2}\kappa^2\right)|S|\right) \frac{2}{\pi} h^\alpha \Gamma\left(\frac{2}{\alpha}\right) \\ &= |1 + \hat{h}| \left|1 - \frac{1}{2}\kappa^2\right| \left(1 + \left(\kappa + \frac{1}{2}\kappa^2\right) \frac{2}{\pi} \Gamma\left(\frac{2}{\alpha}\right)\right)\end{aligned}$$

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